

Mathematics

ON CONNECTION OF ONE CLASS OF ONE-DIMENSIONAL
PSEUDODIFFERENTIAL OPERATORS WITH SINGULAR INTEGRAL
OPERATORS

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The paper discusses a homogeneous one-dimensional pseudodifferential equation with a symbol of the form

$$A(x, \xi) = A_0(\xi) + \sum_{k=1}^N \operatorname{th} \frac{\pi}{\alpha} \left(x - \lambda_k + i \frac{\alpha \beta}{2} \right) A_k(\xi)$$

$$(x, \xi, \lambda_k \in \mathbb{R}, \alpha > 0, -1 < \beta < 1, k = 1, 2, \dots, N),$$

where $A_k(\xi)$ ($k = 0, 1, \dots, N$) are locally integrable functions from class of symbols of non-negative order r .

The method of bringing the pseudodifferential equation to a system of one-dimensional singular integral equations with Cauchy's kernel is proposed.

Keywords: pseudodifferential operator, factorization of matrix-function.

1⁰. The paper is devoted to the study of one-dimensional pseudodifferential operators $A(x, D) = F_{\xi \rightarrow x}^{-1} A(x, \xi) F_{x \rightarrow \xi}$ with $A(x, \xi) = 1 + A_0(\xi) + \sum_{k=1}^N \varphi(x, \lambda_k) A_k(\xi)$

$(x, \xi \in \mathbb{R})$ symbols, where $\varphi(x, \lambda_k) = \operatorname{th} \frac{\pi}{\alpha} \left(x - \lambda_k + i \frac{\alpha \beta}{2} \right)$ ($x \in \mathbb{R}, \alpha > 0, -1 < \beta < 1,$

$\lambda_k \in \mathbb{R}, k = 1, 2, \dots, N$). It is assumed that $A_k(\xi) \in S_r^0$ ($k = 0, 1, \dots, N$) for some $r \geq 0$, where S_r^0 is a set of locally integrable on \mathbb{R} functions f , which correspond to the following condition: $|f| \leq c(1 + |\xi|)^r$.

Earlier, the cases of $r = 0$ and $N = 1$ had been discussed in [1] and [2] correspondingly. In this paper the study of solvability of equation $A(x, D)y = 0$ is brought to solvability of some characteristic system of one-dimensional singular integral equations with Cauchy's kernel. Theory of matrix singular integral operators is currently quite well developed (e.g. see [3–7]).

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2⁰. Let $H_r(\mathbb{R})$ ($r \in \mathbb{R}$) be the Sobolev–Slobodetsky space of generalized functions u , the Fourier transformation \hat{u} of which belongs to the space $L_2(\mathbb{R}, (1+|x|)^r)$. Below, we denote by A_u the operator of multiplication by matrix-function u ($A_u y = uy$). It is well known (e.g. see [8]) that a pseudodifferential operator $A(x, D)$ with symbol $A(x, \xi)$: $A(x, D)u = \int_{-\infty}^{\infty} e^{-ix\xi} A(x, \xi) \hat{u}(\xi) d\xi$ ($u \in C_0^\infty(\mathbb{R})$) may be extended up to a continuous operator from $H_r(\mathbb{R})$ to $L_2(\mathbb{R})$. We assume below that $A(x, D)$ acts on $H_r(\mathbb{R})$. For a function y , defined on $\mathbb{R}_+ = (0, +\infty)$ through $\gamma_k y$ ($k = 0, 1, \dots, N$), we introduce the function $e^{s_k x} y(e^{\alpha x})$, where $\sigma = \alpha(\beta + 1) / 2$ and $s_k = \sigma + i\lambda_k$ ($\lambda_0 \in \mathbb{R}$). It is obvious, that the operators γ_k are continuous mappings from $L_2(\mathbb{R}_+, \rho)$ to $L_2(\mathbb{R})$, where $\rho(t) = t^\beta$ ($-1 < \beta < 1$) for $t \geq 0$.

$h(x) = \alpha^{-1} \ln x$ ($x \in \mathbb{R}_+$) and $\Phi(\xi) = (1 + |\xi|)^r$ are given. We define functions Ψ , Ψ_k ($k = 0, 1, \dots, N$) as $\Psi = \Phi \circ h$, $\Psi_k = A_k \circ h$. Let $M_r(\mathbb{R})$ be some direct complement to linear space $H_r(\mathbb{R})$ in space $L_2(\mathbb{R})$, and $\pi_1 : L_2(\mathbb{R}) \rightarrow H_r(\mathbb{R})$, $\pi_2 : L_2(\mathbb{R}) \rightarrow M_r(\mathbb{R})$ be operators of projecting linked with $\pi_1 y + \pi_2 y = y$ for $y \in L_2(\mathbb{R})$. Let's define spaces $W_k = \{f; \Psi_k^{-1} f \in L_2(\mathbb{R}_+, \rho)\}$ ($k = 1, 2, \dots, N$), $W = \{f; \Psi^{-1} f \in L_2(\mathbb{R}_+, \rho)\}$ and operator $\pi_3 : W \rightarrow L_2(\mathbb{R}_+, \rho)$ acting identically on $L_2(\mathbb{R}_+, \rho) \cap W$. Let S_Γ be operator of singular integration along the contour Γ , i.e. $(S_\Gamma y)(t) = \frac{1}{\pi i} v.p. \int_\Gamma y(\tau) \frac{d\tau}{\tau - t}$ ($t \in \Gamma$).

Let's define the functions $\Delta_{k,l}(t) = \exp\left\{i \frac{\lambda_l - \lambda_k}{\alpha} \ln t\right\}$ ($k, l = 1, 2, \dots, N$). Consider a collection of operators: $\omega_1 : L_2^N(\mathbb{R}_+, \rho) \rightarrow H_r(\mathbb{R})$, $\omega_2 : H_r(\mathbb{R}) \rightarrow L_2^N(\mathbb{R}_+, \rho)$, $\omega_3 : L_2^N(\mathbb{R}_+, \rho) \rightarrow M_r(\mathbb{R})$, $\omega_4 : W_1 \oplus W_2 \oplus \dots \oplus W_N \rightarrow L_2^N(\mathbb{R}_+, \rho)$ and $\omega_5 : W_1 \oplus W_2 \oplus \dots \oplus W_N \rightarrow L_2^N(\mathbb{R}_-, \rho(|t|))$ ($\mathbb{R}_- = \mathbb{R} \setminus \mathbb{R}_+$) defined by the following equalities:

$$\omega_1 = [\pi_1 F^{-1} \gamma_1 \quad \pi_1 F^{-1} \gamma_2 \quad \dots \quad \pi_1 F^{-1} \gamma_N],$$

$$\omega_2 = \begin{bmatrix} \gamma_1^{-1} F A_0(D) + S_{\mathbb{R}_+} \gamma_1^{-1} F A_1(D) \\ S_{\mathbb{R}_+} \gamma_2^{-1} F A_2(D) \\ \vdots \\ S_{\mathbb{R}_+} \gamma_N^{-1} F A_N(D) \end{bmatrix}, \quad \omega_3 = [\pi_2 F^{-1} \gamma_1 \quad \pi_2 F^{-1} \gamma_2 \quad \dots \quad \pi_2 F^{-1} \gamma_N],$$

$$\omega_4 = \begin{bmatrix} A_{\Psi_1^{-1}} & 0 & \cdots & 0 \\ 0 & A_{\Psi_2^{-1}} & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & A_{\Psi_N^{-1}} \end{bmatrix}, \quad \omega_5 = \begin{bmatrix} \omega_{11}^5 & \cdots & \omega_{1N}^5 \\ \vdots & & \vdots \\ \omega_{N1}^5 & \cdots & \omega_{NN}^5 \end{bmatrix},$$

where operators $\omega_{ij}^5: W_j \rightarrow L_2^N(\mathbb{R}_-, \rho(|t|))$ ($i, j=1, 2, \dots, N$) are defined by equalities $(\omega_{ij}^5 v)(t) = \frac{1}{\pi i} \int_0^\infty \tilde{A}_i(\tau) \left(\pi_3 A_\Psi \gamma_0^{-1} \gamma_j A_{\Psi_j^{-1}} v \right) (\tau) \frac{d\tau}{\tau - t}$, and $\tilde{A}_i = \Delta_{i,0} \Psi_i \Psi_i^{-1}$ on \mathbb{R}_+ . Note, that pseudodifferential operator $A(x, D)$ ($A(x, D): H_r(\mathbb{R}) \rightarrow H_r(\mathbb{R}) \oplus M_r(\mathbb{R})$) could be represented by the equality

$$A(x, D) = \begin{bmatrix} I_{H_r(\mathbb{R})} + \omega_1 \omega_2 \\ \omega_3 \omega_2 \end{bmatrix}.$$

Let's also consider the linear operators

$$T_{12}: L_2^N(\mathbb{R}_+, \rho) \oplus M_r(\mathbb{R}) \oplus L_2^N(\mathbb{R}_-, \rho(|t|)) \rightarrow H_r(\mathbb{R}) \oplus M_r(\mathbb{R}),$$

$$T_{21}: H_r(\mathbb{R}) \rightarrow W_1 \oplus W_2 \oplus \cdots \oplus W_N \oplus L_2^N(\mathbb{R}_-, \rho(|t|)),$$

$$T_{22}: L_2^N(\mathbb{R}_+, \rho) \oplus M_r(\mathbb{R}) \oplus L_2^N(\mathbb{R}_-, \rho(|t|)) \rightarrow W_1 \oplus W_2 \oplus \cdots \oplus W_N \oplus L_2^N(\mathbb{R}_-, \rho(|t|)),$$

$$K_{11}: H_r(\mathbb{R}) \oplus M_r(\mathbb{R}) \rightarrow H_r(\mathbb{R}),$$

$$K_{12}: W_1 \oplus W_2 \oplus \cdots \oplus W_N \oplus L_2^N(\mathbb{R}_-, \rho(|t|)) \rightarrow H_r(\mathbb{R}),$$

$$K_{21}: H_r(\mathbb{R}) \oplus M_r(\mathbb{R}) \rightarrow L_2^N(\mathbb{R}_+, \rho) \oplus M_r(\mathbb{R}) \oplus L_2^N(\mathbb{R}_-, \rho(|t|)),$$

$$\tilde{K}: W_1 \oplus W_2 \oplus \cdots \oplus W_N \oplus L_2^N(\mathbb{R}_-, \rho(|t|)) \rightarrow L_2^N(\mathbb{R}_+, \rho) \oplus M_r(\mathbb{R}) \oplus L_2^N(\mathbb{R}_-, \rho(|t|)),$$

defined by equalities

$$T_{12} = \begin{bmatrix} -\omega_1 & 0 & 0 \\ -\omega_3 & I_{M_r(\mathbb{R})} & 0 \end{bmatrix}, \quad T_{21} = \begin{bmatrix} -\omega_4^{-1} \omega_2 \\ \omega_5 \omega_4^{-1} \omega_2 \end{bmatrix}, \quad T_{22} = \begin{bmatrix} \omega_4^{-1} & 0 & 0 \\ -\omega_5 \omega_4^{-1} & 0 & I_{L_2^N(\mathbb{R}_-, \rho(|t|))} \end{bmatrix},$$

$$K_{11} = \begin{bmatrix} I_{H_r(\mathbb{R})} & 0 \end{bmatrix}, \quad K_{12} = \begin{bmatrix} \omega_1 \omega_4 & 0 \end{bmatrix}, \quad K_{21} = \begin{bmatrix} \omega_2 & 0 \\ 0 & I_{M_r(\mathbb{R})} \\ 0 & 0 \end{bmatrix},$$

$$\tilde{K} = \begin{bmatrix} \omega_4 + \omega_2 \omega_1 \omega_4 & 0 \\ \omega_3 \omega_4 & 0 \\ \omega_5 & I_{L_2^N(\mathbb{R}_-, \rho(|t|))} \end{bmatrix}.$$

By direct calculation it is easy to verify the equality

$$\begin{bmatrix} A(x, D) & T_{12} \\ T_{21} & T_{22} \end{bmatrix} = \begin{bmatrix} K_{11} & K_{12} \\ K_{21} & \tilde{K} \end{bmatrix}^{-1}.$$

The next lemma follows from the results of the paper [2]:

Lemma 1. Spaces $\text{Ker}A(x, D)$ and $\text{Ker}\tilde{K}$ are isomorphic, besides the following equalities are true $\text{Ker}A(x, D) = K_{12}\text{Ker}\tilde{K}$, $\text{Ker}\tilde{K} = T_{21}\text{Ker}A(x, D)$.

3⁰. Operator $U : W_1 \oplus W_2 \oplus \dots \oplus W_N \rightarrow W \oplus L_2^{N-1}(\mathbb{R}_+, \rho)$ is defined through the following equality:

$$U = \begin{bmatrix} A_\Psi \gamma_0^{-1} \gamma_1 A_{\Psi_1^{-1}} & A_\Psi \gamma_0^{-1} \gamma_2 A_{\Psi_2^{-1}} & A_\Psi \gamma_0^{-1} \gamma_3 A_{\Psi_3^{-1}} & \dots & A_\Psi \gamma_0^{-1} \gamma_N A_{\Psi_N^{-1}} \\ 0 & A_{\Psi_2^{-1}} & 0 & \dots & 0 \\ 0 & 0 & A_{\Psi_3^{-1}} & \ddots & \vdots \\ \vdots & \vdots & \ddots & \ddots & 0 \\ 0 & 0 & \dots & 0 & A_{\Psi_N^{-1}} \end{bmatrix}.$$

Let's define also the operator $K = A_M + S_{\mathbb{R}} A_N : L_2^N(\mathbb{R}, \rho(|t|)) \rightarrow L_2^N(\mathbb{R}, \rho(|t|))$, where

$$M = \begin{bmatrix} \Psi^{-1} \Delta_{1,0} + \Psi_0 \Psi^{-1} \Delta_{1,0} & -\Delta_{1,2} & -\Delta_{1,3} & \dots & -\Delta_{1,N} \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \ddots & \vdots \\ \vdots & \vdots & \ddots & \ddots & 0 \\ 0 & 0 & \dots & 0 & 1 \end{bmatrix},$$

$$N = \begin{bmatrix} \Psi_1 \Psi^{-1} \Delta_{1,0} & 0 & \dots & 0 \\ \Psi_2 \Psi^{-1} \Delta_{2,0} & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ \Psi_N \Psi^{-1} \Delta_{N,0} & 0 & \dots & 0 \end{bmatrix}$$

on \mathbb{R}_+ , and correspondingly equal to unit and zero matrices on \mathbb{R}_- .

Lemma 2. If vector-function $z = (z_+, z_-)^T$, where $z_+ \in W_1 \oplus W_2 \oplus \dots \oplus W_N$ and $z_- \in L_2^N(\mathbb{R}_-, \rho(|t|))$, is a solution of the equation $\tilde{K}z = 0$, then vector-function u , being equal to Uz_+ on \mathbb{R}_+ and to z_- on \mathbb{R}_- , is a solution of equation $Ku = 0$.

Vice versa, if vector-function u is a solution of the equation $Ku = 0$, then vector-function z , being equal to $U^{-1}u$ on \mathbb{R}_+ and to u on \mathbb{R}_- , is a solution of the equation $\tilde{K}z = 0$.

Proof. First of all let's note that for the function f , defined on \mathbb{R}_+ , the condition $f \in L_2(\mathbb{R}_+, \rho)$ is equivalent to $F^{-1} \gamma_0 A_{\Psi^{-1}} f \in H_r(\mathbb{R})$. Indeed, let $F^{-1} \gamma_0 A_{\Psi^{-1}} f \in H_r(\mathbb{R})$, consequently $\Phi(D) F^{-1} \gamma_0 A_{\Psi^{-1}} f \in L_2(\mathbb{R})$. Hence

$$\gamma_0^{-1} F \Phi(D) F^{-1} \gamma_0 A_{\Psi^{-1}} f = \gamma_0^{-1} A_\Phi \gamma_0 A_{\Psi^{-1}} f = f \in L_2(\mathbb{R}_+, \rho).$$

Vice versa, let $f \in L_2(\mathbb{R}_+, \rho)$. Consequently $F^{-1} \gamma_0 f \in L_2(\mathbb{R})$, and therefore $\Phi^{-1}(D) F^{-1} \gamma_0 f = F^{-1} A_{\Phi^{-1}} \gamma_0 f = F^{-1} \gamma_0 A_{\Psi^{-1}} f \in H_r(\mathbb{R})$.

For the vector-function $z = (z_+, z_-)^T$, which is the solution for the equation $\tilde{K}z = 0$, the following equalities are true:

$$\omega_4 z_+ + \omega_2 \omega_1 \omega_4 z_+ = 0, \quad \omega_3 \omega_4 z_+ = 0, \quad \omega_5 z_+ + z_- = 0. \quad (1)$$

Let $U_{z_+} = (u_1^+, u_2^+, \dots, u_N^+)^T$. Since from the second equality of (1) it follows that $F^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+ \in H_r(\mathbb{R})$, then $u_1^+ \in L_2(\mathbb{R}_+, \rho)$. From the definitions of spaces W_k ($k = 2, \dots, N$) it follows that $u_k^+ \in L_2(\mathbb{R}_+, \rho)$ ($k = 2, \dots, N$). Thus $u \in L_2^N(\mathbb{R}, \rho(|t|))$. First equality (1) could be represented in the following form:

$$\begin{aligned} & \gamma_1^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+ + \gamma_1^{-1} F A_0(D) \pi_1 F^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+ - \gamma_1^{-1} \gamma_2 u_2^+ - \dots - \gamma_1^{-1} \gamma_N u_N^+ + \\ & \quad + S_{\mathbb{R}_+} \gamma_1^{-1} F A_1(D) \pi_1 F^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+ = 0, \\ & u_k^+ + S_{\mathbb{R}_+} \gamma_k^{-1} F A_k(D) \pi_1 F^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+ = 0 \quad (k = 2, \dots, N). \end{aligned} \quad (2)$$

Taking into account that $\pi_1 F^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+ = F^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+$, we find

$$\begin{aligned} & \gamma_1^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+ + \gamma_1^{-1} F A_0(D) F^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+ - \gamma_1^{-1} \gamma_2 u_2^+ - \dots - \gamma_1^{-1} \gamma_N u_N^+ + \\ & \quad + S_{\mathbb{R}_+} \gamma_1^{-1} F A_1(D) F^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+ = 0, \\ & u_k^+ + S_{\mathbb{R}_+} \gamma_k^{-1} F A_k(D) F^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+ = 0 \quad (k = 2, \dots, N). \end{aligned} \quad (3)$$

Third equality (1) could be represented in the form

$$\frac{1}{\pi i} \int_0^\infty \tilde{A}_k(\tau) (\pi_3 u_1^+) (\tau) \frac{d\tau}{\tau - t} + z_k^- = 0 \quad (k = 1, \dots, N). \quad (4)$$

Now taking into account that $\pi_3 u_1^+ = u_1^+$, we find

$$\frac{1}{\pi i} \int_0^\infty \tilde{A}_k(\tau) u_1^+(\tau) \frac{d\tau}{\tau - t} + z_k^- = 0 \quad (k = 1, \dots, N). \quad (5)$$

The equalities (3) and (5) means that $Ku = 0$.

Let now $Ku = 0$. Then, if $u_+ = (u_1^+, u_2^+, \dots, u_N^+)^T$ is equal to vector-function u on \mathbb{R}_+ , and $z_- = (z_1^-, z_2^-, \dots, z_N^-)^T$ is equal to vector-function u on \mathbb{R}_- , the equality $Ku = 0$ is equivalent to (3) and (5). Taking into account that $u_1^+ \in L_2(\mathbb{R}_+, \rho)$, we find that $F^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+ \in H_r(\mathbb{R})$, i.e. $\pi_1 F^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+ = F^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+$, $\pi_2 F^{-1} \gamma_0 \mathcal{A}_{\psi^{-1}} u_1^+ = 0$ and $\pi_3 u_1^+ = u_1^+$. From here follows the truth of the equalities (2) and (4). Consequently $z_+ = U^{-1} u_+$ and z_- suffice the equalities (1), which means $\tilde{K}z = 0$.

From Lemmas 1 and 2 follows

Theorem 1. If $A(x, D)y = 0$, and functions $u_k(x)$ when $x > 0$ are defined through the equalities

$$u_1 = \mathcal{A}_\psi \gamma_0^{-1} F y, \quad u_k = -S_{\mathbb{R}_+} \gamma_k^{-1} F A_k(D) y \quad (k = 2, \dots, N),$$

then vector-function u , defined through the equality $u = (u_1, u_2, \dots, u_N)^T$ when $x > 0$ and equality $u(x) = -\frac{1}{\pi i} \int_0^\infty N(t)u(t) \frac{dt}{t-x}$ when $x < 0$, suffice to equation $Ku = 0$.

Vice versa, if for the vector-function $u = (u_1, u_2, \dots, u_N)^T$ $Ku = 0$, then function $y(x) = \int_{-\infty}^\infty e^{-ixt} e^{st} \Phi_0^{-1}(t) u_1(e^{\alpha t}) dt$ suffice to equation $A(x, D)y = 0$.

4^o. Due to Theorem 1 the solution of equation $A(x, D)y = 0$ in class $H_r(\mathbb{R})$ is brought to description of set $\text{Ker}K$.

Let $P_{\mathbb{R}}^\pm = I \pm S_{\mathbb{R}}$ by analytic projectors. Let's assume that $(M \pm N)^{-1} \in L_\infty$. Operator K could be represented in the form $K = P_{\mathbb{R}}^+ A_{M+N} + P_{\mathbb{R}}^- A_{M-N} = (P_{\mathbb{R}}^+ A_G + P_{\mathbb{R}}^-) A_{M-N}$, where $G = (M + N)(M - N)^{-1}$. Let $\tilde{\Psi} = \left(1 + \Psi_0 - \sum_{i=1}^N \Psi_i\right)^{-1}$. Through direct calculation it is easy to get convinced that

$$G = \begin{bmatrix} 1 + 2\Psi_1\tilde{\Psi} & 2\Psi_1\tilde{\Psi}\Delta_{1,2} & 2\Psi_1\tilde{\Psi}\Delta_{1,3} & \dots & 2\Psi_1\tilde{\Psi}\Delta_{1,N} \\ 2\Psi_2\tilde{\Psi}\Delta_{2,1} & 1 + 2\Psi_2\tilde{\Psi} & 2\Psi_2\tilde{\Psi}\Delta_{2,3} & \dots & 2\Psi_2\tilde{\Psi}\Delta_{2,N} \\ 2\Psi_3\tilde{\Psi}\Delta_{3,1} & 2\Psi_3\tilde{\Psi}\Delta_{3,2} & 1 + 2\Psi_3\tilde{\Psi} & & \\ \vdots & \vdots & & \ddots & \\ 2\Psi_N\tilde{\Psi}\Delta_{N,1} & 2\Psi_N\tilde{\Psi}\Delta_{N,2} & & & 1 + 2\Psi_N\tilde{\Psi} \end{bmatrix}$$

on \mathbb{R}_+ , and coincides with the unit matrix on \mathbb{R}_- .

Let $L_2^\pm(\mathbb{R}) = P_{\mathbb{R}}^\pm(L_2(\mathbb{R}))$. Under the factorization of the matrix-function G in space $L_2(\mathbb{R}, \rho(|t|))$ we understand the representation $G(t) = G_-(t)\Xi(t)G_+(t)$ ($t \in \mathbb{R}$), where

$$\frac{1}{t-i}(t^{\beta/2}G_-(t))^{\pm 1} \in L_2^-(\mathbb{R}), \quad \frac{1}{t+i}(t^{-\beta/2}G_+(t))^{\pm 1} \in L_2^+(\mathbb{R}),$$

$$\Xi(t) = \text{diag} \left(\left(\frac{t-i}{t+i} \right)^{k_1} \dots \left(\frac{t-i}{t+i} \right)^{k_N} \right),$$

operator $A_{G_+}^{-1}S_{\mathbb{R}}A_{G_+}$ is bounded in $L_2^N(\mathbb{R})$, and $k_1 \geq \dots \geq k_N$ are the integers named particular indices of matrix-function G . Here the belongness to the functional classes is considered element-wise.

Using the standard considerations (see [2]) and general theory of matrix singular operators (see [5–7]), in those cases when matrix-function G allows factorization in $L_2(\mathbb{R}, \rho(|t|))$, kernel of operator K allows description in terms of

factors of matrix-function G . Precisely, if $k_1 \geq k_2 \geq \dots \geq k_s \geq 0 > k_{s+1} \geq \dots \geq k_N$, then $\text{Ker}K$ consists from vector-functions of a form $u = (M - N)^{-1}G_+^{-1}p$, where $p = (p_1, \dots, p_N)^T$ is a polynomial vector for which the following conditions are true: $p_1 = p_2 = \dots = p_s = 0$, and $\deg p_j \leq |k_j| - 1$ ($j = s + 1, \dots, N$). Particularly, $\dim \text{Ker}K$ is equal to the absolute value of sum of the negative particular indices.

As an example let's note that equation $y''(x) + \sum_{k=1}^N c_k \varphi(x, \lambda_k) y(x) = 0$ ($c_k \in \mathbb{C}$) is brought to the factorization of the matrix-function

$$G = \begin{bmatrix} 1 + a_1 \tilde{\Psi} & a_1 \tilde{\Psi} \Delta_{1,2} & a_1 \tilde{\Psi} \Delta_{1,3} & \dots & a_1 \tilde{\Psi} \Delta_{1,N} \\ a_2 \tilde{\Psi} \Delta_{2,1} & 1 + a_2 \tilde{\Psi} & a_2 \tilde{\Psi} \Delta_{2,3} & \dots & a_2 \tilde{\Psi} \Delta_{2,N} \\ a_3 \tilde{\Psi} \Delta_{3,1} & a_3 \tilde{\Psi} \Delta_{3,2} & 1 + a_3 \tilde{\Psi} & & \\ \vdots & \vdots & & \ddots & \\ a_N \tilde{\Psi} \Delta_{N,1} & a_N \tilde{\Psi} \Delta_{N,2} & & & 1 + a_N \tilde{\Psi} \end{bmatrix}$$

on \mathbb{R}_+ , and coincides with the unit matrix on \mathbb{R}_- , where $a_k = 2c_k$ ($k = 1, 2, \dots, N$), and $\tilde{\Psi}(x) = -(\alpha^{-1} \ln x)^2 - \sum_{k=1}^N c_k$.

5⁰. Let's consider the pseudodifferential operator $A(x, D)$ with a symbol of the form $A(x, \xi) = 1 + P(\varphi(x, \lambda)) A_0(\xi)$, where $P(z) = \prod_{k=1}^N (z - \nu_k)$ is an arbitrary polynomial. Let's define operators

$$\tilde{\omega}_1 = \pi_1 F^{-1} \gamma : L_2(\mathbb{R}_+, \rho) \rightarrow H_r(\mathbb{R}), \quad \tilde{\omega}_2 = \sum_{k=0}^N c_k S_{\mathbb{R}_+}^k \gamma^{-1} F A_0(D) : H_r(\mathbb{R}) \rightarrow L_2(\mathbb{R}_+, \rho),$$

$$\tilde{\omega}_3 = \pi_2 F^{-1} \gamma : L_2(\mathbb{R}_+, \rho) \rightarrow M_r(\mathbb{R}), \quad \tilde{\omega}_4 = A_{\nu^{-1}} : \tilde{W} \rightarrow L_2(\mathbb{R}_+, \rho),$$

where $\tilde{W} = \{f : A_0^{-1}(h)f \in L_2(\mathbb{R}_+, \rho)\}$.

By direct calculation, we get the equality

$$\begin{bmatrix} I_{H_r(\mathbb{R})} + \tilde{\omega}_1 \tilde{\omega}_2 & -\tilde{\omega}_1 & 0 \\ \tilde{\omega}_3 \tilde{\omega}_2 & -\tilde{\omega}_3 & I_{M_r(\mathbb{R})} \\ -\tilde{\omega}_4^{-1} \tilde{\omega}_2 & \tilde{\omega}_4^{-1} & 0 \end{bmatrix}^{-1} = \begin{bmatrix} I_{H_r(\mathbb{R})} & 0 & \tilde{\omega}_1 \tilde{\omega}_4 \\ \tilde{\omega}_2 & 0 & \tilde{\omega}_4 + \tilde{\omega}_2 \tilde{\omega}_1 \tilde{\omega}_4 \\ 0 & I_{M_r(\mathbb{R})} & \tilde{\omega}_3 \tilde{\omega}_4 \end{bmatrix}.$$

Using this matrix identity one can prove a result similar to Theorem 1, where operator K plays role of the singular operator, defined through the equality

$$Kz = A_0^{-1}(h)z + \sum_{k=0}^N c_k S_{\mathbb{R}_+}^k z.$$

Following § 3.1 of [1], the investigation of the pseudodifferential equation $A(x, D)y = 0$ is brought to the factorization of the matrix-function $G = G_+^{-1}G_-$, where

$$G_{\pm} = \begin{bmatrix} 1 & (\pm 1 - \nu_1)A(h) & 0 & \cdots & 0 & 0 \\ 0 & 1 & \nu_2 \mp 1 & \cdots & 0 & 0 \\ 0 & 0 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \cdots & & \\ 0 & 0 & 0 & \cdots & 1 & \nu_{N-1} \mp 1 \\ \nu_N \mp 1 & 0 & 0 & \cdots & 0 & 1 \end{bmatrix}$$

when $x > 0$, and G_{\pm} are equal to unit matrix when $x < 0$.

Particularly, the solution of the differential equation $y''(x) + (\varphi(x, \lambda) - \nu_1)(\varphi(x, \lambda) - \nu_2)y(x) = 0$ from class $H_r(\mathbb{R})$ could be expressed by factors of matrix

$$G = \begin{bmatrix} \frac{1 + A_0(h)(-1 + \nu_1)(1 + \nu_2)}{1 + A_0(h)(-1 + \nu_1)(-1 + \nu_2)} & -\frac{2A_0(h)}{1 + A_0(h)(-1 + \nu_1)(-1 + \nu_2)} \\ \frac{2}{1 + A_0(h)(-1 + \nu_1)(-1 + \nu_2)} & \frac{1 + A_0(h)(1 + \nu_1)(-1 + \nu_2)}{1 + A_0(h)(-1 + \nu_1)(-1 + \nu_2)} \end{bmatrix}$$

on \mathbb{R}_+ , and coincides with the unit matrix on \mathbb{R}_- .

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Միաչափ պսևդոդիֆերենցիալ օպերատորների մի դասի և
սինգուլյար ինտեգրալ օպերատորների կապի մասին

Աշխատանքում դիտարկվում է $A(x, \xi) = A_0(\xi) + \sum_{k=1}^N \operatorname{th} \frac{\pi}{\alpha} \left(x - \lambda_k + i \frac{\alpha \beta}{2} \right) A_k(\xi)$
($x, \xi, \lambda_k \in \mathbb{R}$, $\alpha > 0$, $-1 < \beta < 1$, $k = 1, 2, \dots, N$) տեսքի սիմվոլով համասեռ միաչափ
պսևդոդիֆերենցիալ հավասարում, որտեղ $A_k(\xi)$ -երը ($k = 0, 1, \dots, N$) լոկալ
հանրագումարելի ֆունկցիա-ներ են՝ r ոչ բացասական կարգի սիմվոլների
դասից:

Առաջարկվում է պսևդոդիֆերենցիալ հավասարումը Վոշու կորիզով
միաչափ սինգուլյար ինտեգրալ հավասարումների համակարգի հանգեցնելու
մեթոդ:

О связи одного класса одномерных псевдодифференциальных операторов с
сингулярными интегральными операторами

В работе рассматривается однородное одномерное псевдодифференциальное
уравнение с символом вида $A(x, \xi) = A_0(\xi) + \sum_{k=1}^N \operatorname{th} \frac{\pi}{\alpha} \left(x - \lambda_k + i \frac{\alpha \beta}{2} \right) A_k(\xi)$, ($x, \xi, \lambda_k \in \mathbb{R}$, $\alpha > 0$,
 $-1 < \beta < 1$, $k = 1, 2, \dots, N$), где $A_k(\xi)$ ($k = 0, 1, \dots, N$) – локально суммируемые функции из
класса символов неотрицательного порядка r .

Предлагается метод сведения псевдодифференциального уравнения к системе
одномерных сингулярных интегральных уравнений с ядром Коши.